

UNIT - V CAM'S

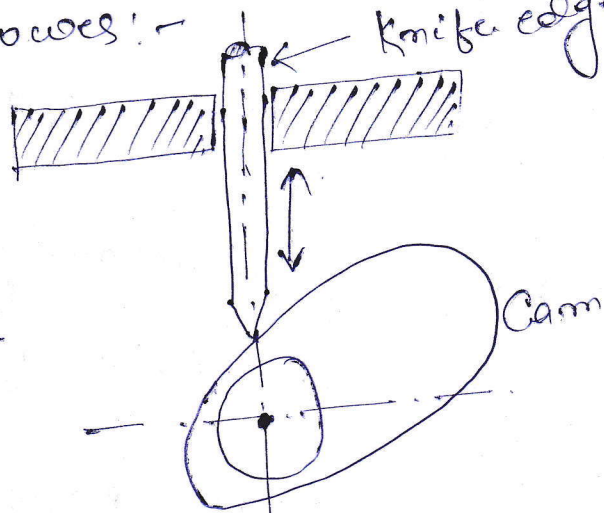
A Cam is a rotating m/c element which gives reciprocating or oscillating motion to another element known as follower.

The cam and follower have a line contact and constitute a higher pair. The cams are widely used for operating the inlet and outlet (exhaust) valve of internal combustion engines, automatic attachments of machineries, paper cutting m/c, spinning and weaving textile machineries, feed mechanism of automatic lathes.

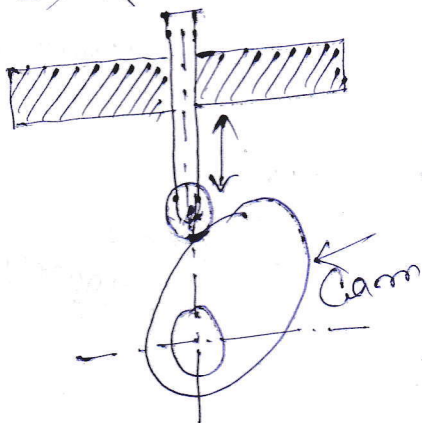
⇒ Types of Followers

(i) According to the surface in contact.

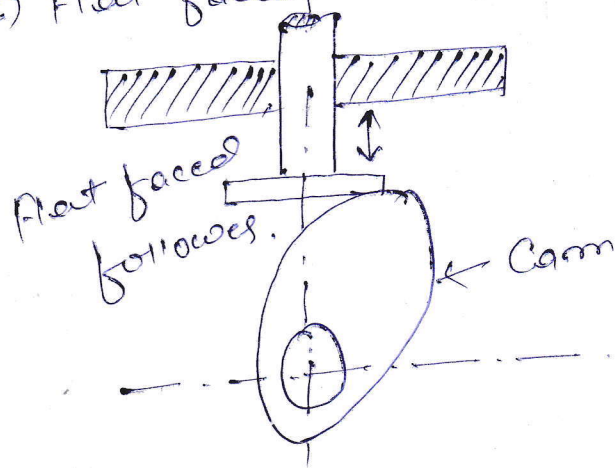
(a) Knife edge follower: -



(b) Roller follower: -

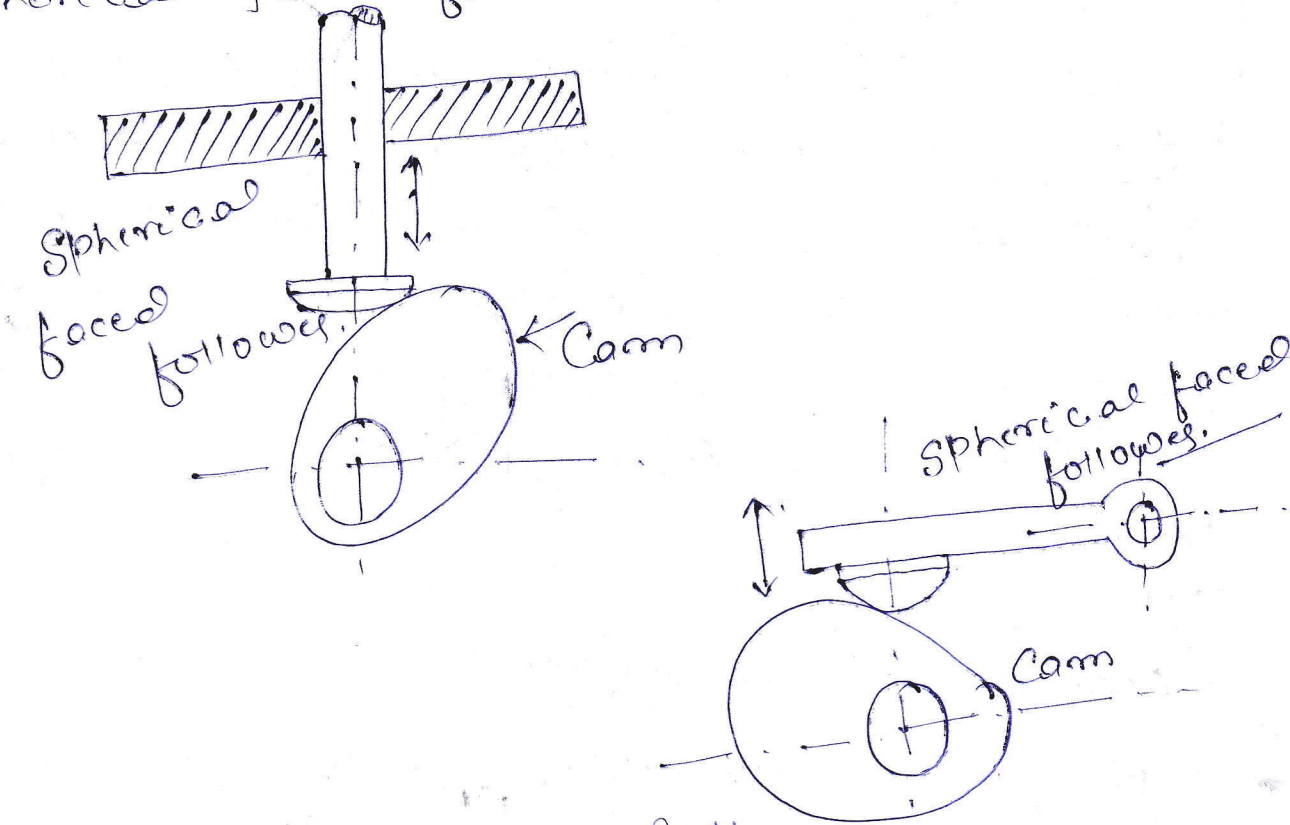


(c) Flat faced or mushroom follower: -



When the flat faced follower is circular, then it is called a mushroom follower.

(ii) Spherical faced followers:—

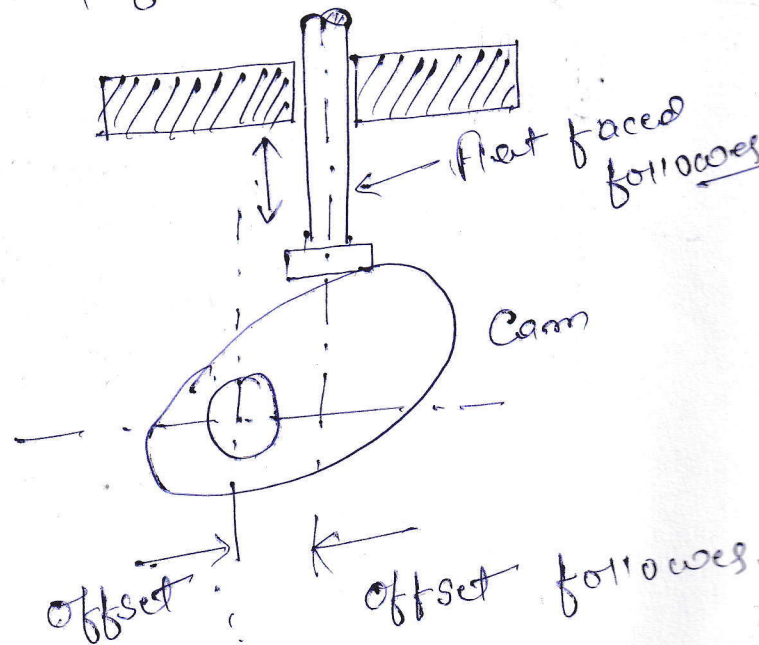


(2) According to the motion of the follower.

- (a) Reciprocating or Translating follower.
- (b) Oscillating or Rotating follower.

(3) According to the path β of the motion of follower

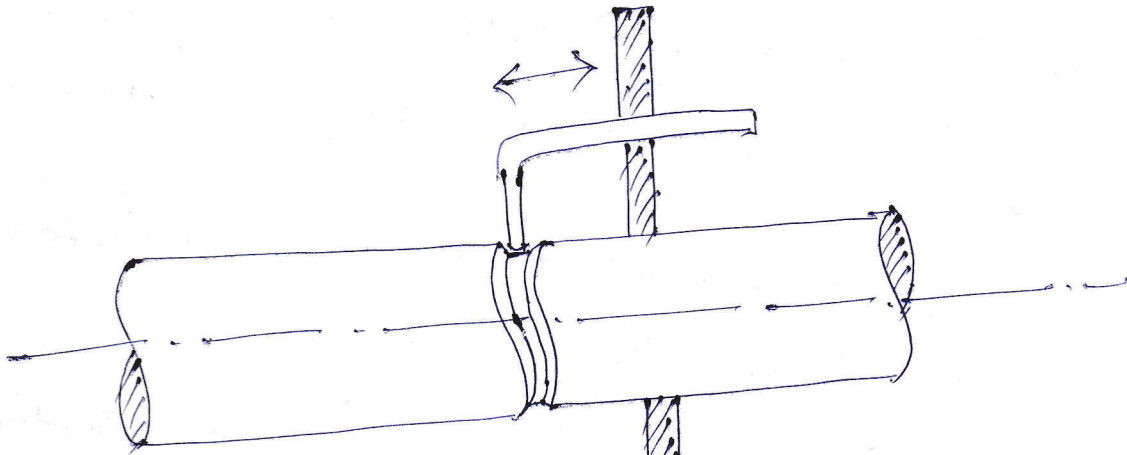
- (a) Radial follower.
- (b) Off-set follower.



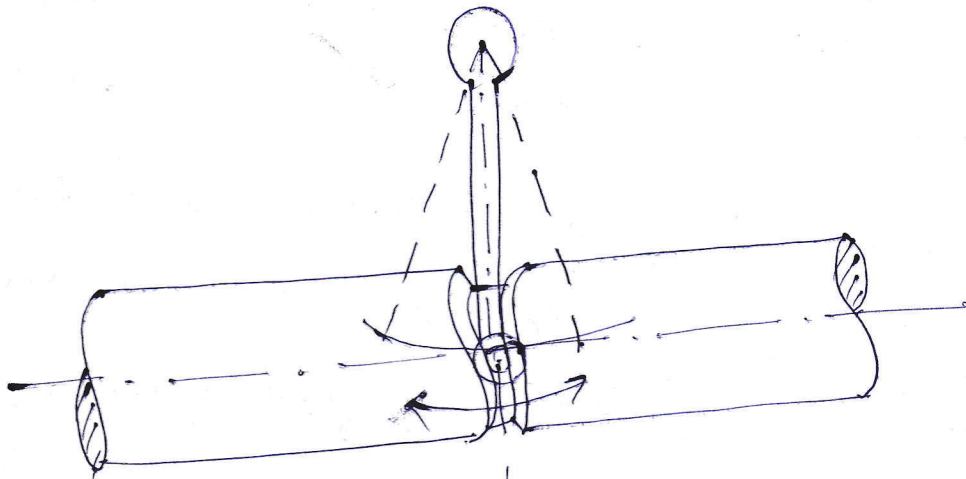
⇒ Types of Cam's.

(i) Radial or disc cam: — In radial cam's, the follower reciprocates or oscillates in a direction perpendicular to the cam axis. The types of follower according to the surface contact is known as radial or disc cam.

(ii) Cylindrical cam: — In cylindrical cam's, the follower reciprocates or oscillates in a direction parallel to the cam axis.



Cylindrical cam with reciprocating follower.



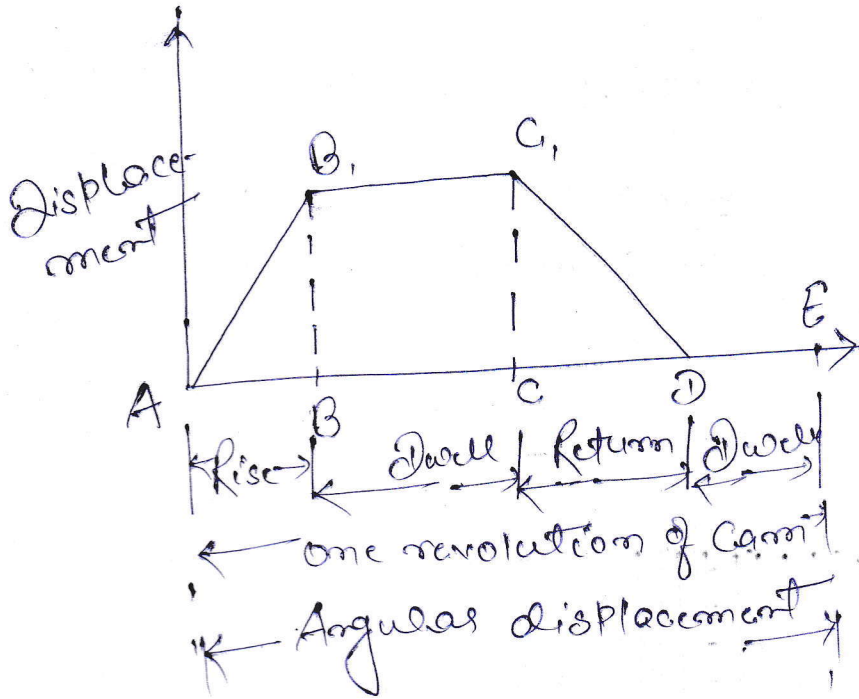
Cylindrical cam with oscillating follower.

⇒ Terms used in Radial Cams.

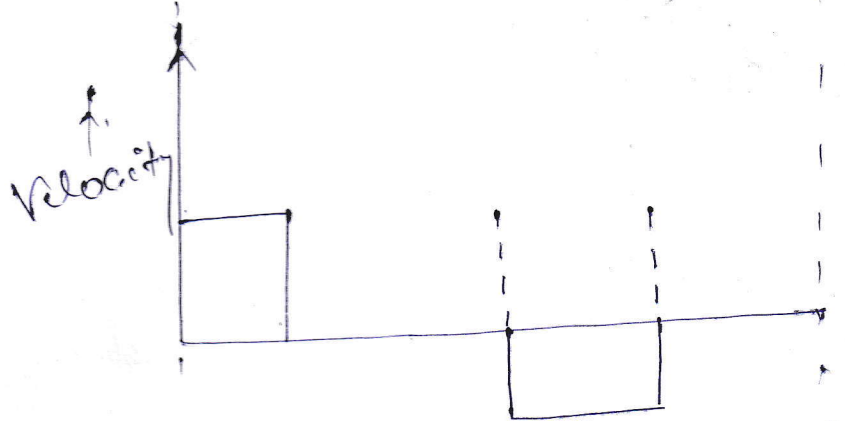
- (i) Base Circle:- It is the Smallest Circle that can be drawn to the Cam Profile.
- (ii) Trace Point:- It is a reference point on the follower and is used to generate the Pitch Curve. In case of knife edge follower the knife edge is represented as a trace point, but in case of roller follower the Centre Point of the roller is known as Trace Point.
- (iii) Pressure angle:- It is the angle between the direction of the follower and a normal to the Pitch Curve.
- (iv) Pitch Point:- It is a point on the Pitch Curve having the maximum pressure angle.
- (v) Pitch Circle:- It is a Circle drawn from the Centre of the Cam through the Pitch Points.
- (vi) Pitch Curve:- It is the Curve generated by the trace point as the follower moves relative to the Cam.
- (vii) Prime Circle:- It is the Smallest Circle drawn from the Centre of the Cam and tangent to the Pitch Curve. For a knife edge and flat faced follower the Prime Circle and the base Circle are identical. For a roller follower, the Prime Circle is larger than the base Circle by the radius of the roller.

(viii) lift of stroke: - It is the maximum travel of the follower from its lowest position to the top most position.

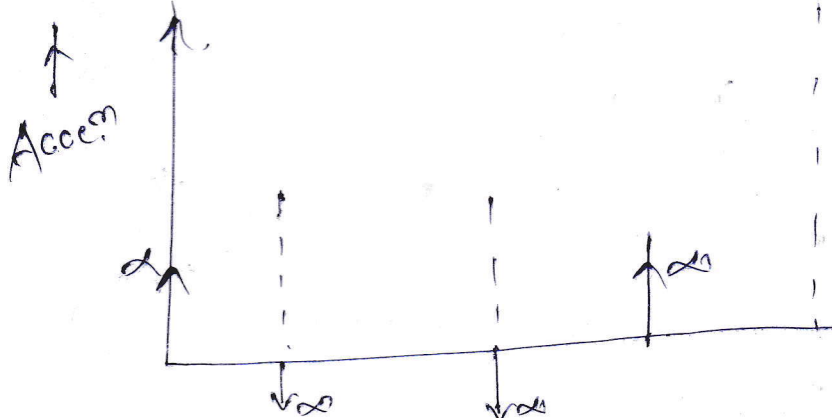
⇒ (i) uniform velocity: -



Displacement diagram.



velocity diagram.



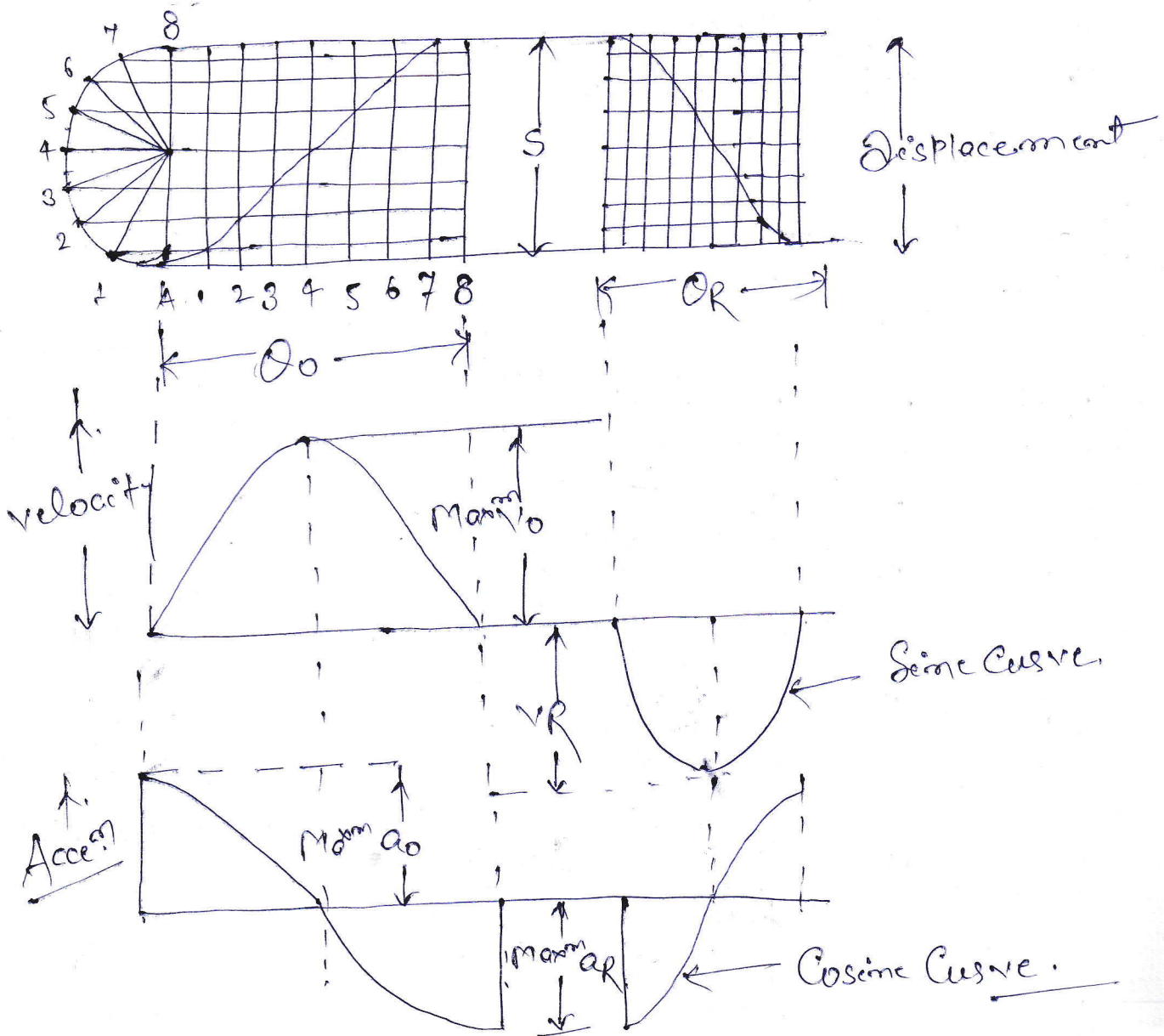
Acceleration diagram.

The follower moves with uniform velocity during its rise and return stroke. So by this reason the displacement curve must be constant.

The periods during which the follower remains at rest are known as dwell period.

⇒ (2) Simple harmonic motion: — The displacement velocity and Acceleration diagrams when follower moves with simple harmonic motions.

Displacement diagram.



Let $S =$ Stroke of the follower

$\theta_0 =$ Angular displacement of the cam during out stroke.

$\theta_r =$ Angular displacement of cam during Ret. stroke.

$\omega =$ Angular velocity of the cam (rad/s).

\therefore Time required for the out stroke of the follower in seconds

$$t_o = \frac{\theta_0}{\omega}$$

Point P' is the projection of point P on the diameter. Point P' executes a simple harmonic motion as the point P rotates.

The motion of the follower is similar to that of point P' .

\therefore Peripheral speed of the point P'

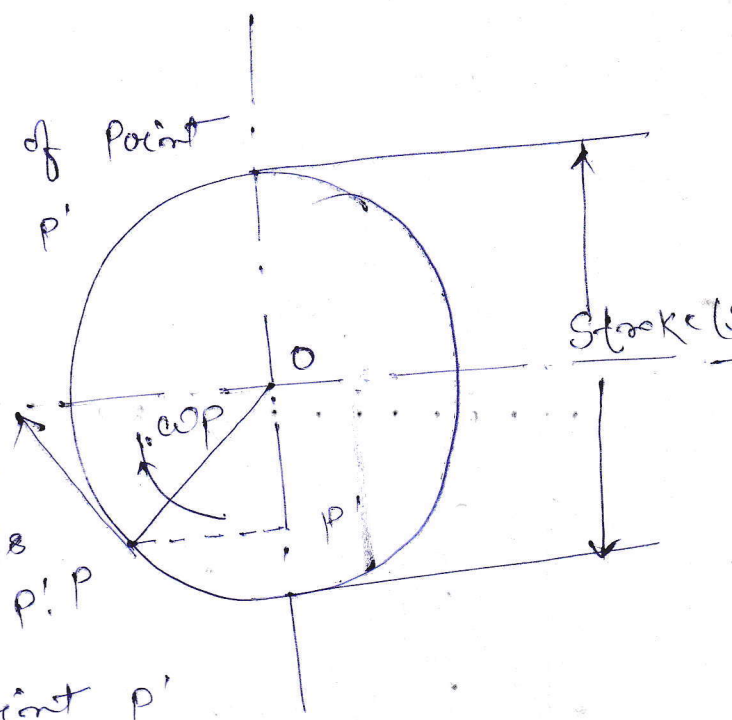
$$v_p = \frac{\pi S}{2} \times \frac{1}{t_o} = \frac{\pi S}{2} \times \frac{\omega}{\theta_0}$$

Max^m velocity of the follower on the outstroke

$$v_o = v_p = \frac{\pi S}{2} \times \frac{\omega}{\theta_0} = \frac{\pi \omega S}{2 \theta_0}$$

\therefore Max^m Accⁿ of the follower on the outstroke

$$a_o = a_p = \frac{\pi^2 \omega^2 S}{2 (\theta_0)^2}$$



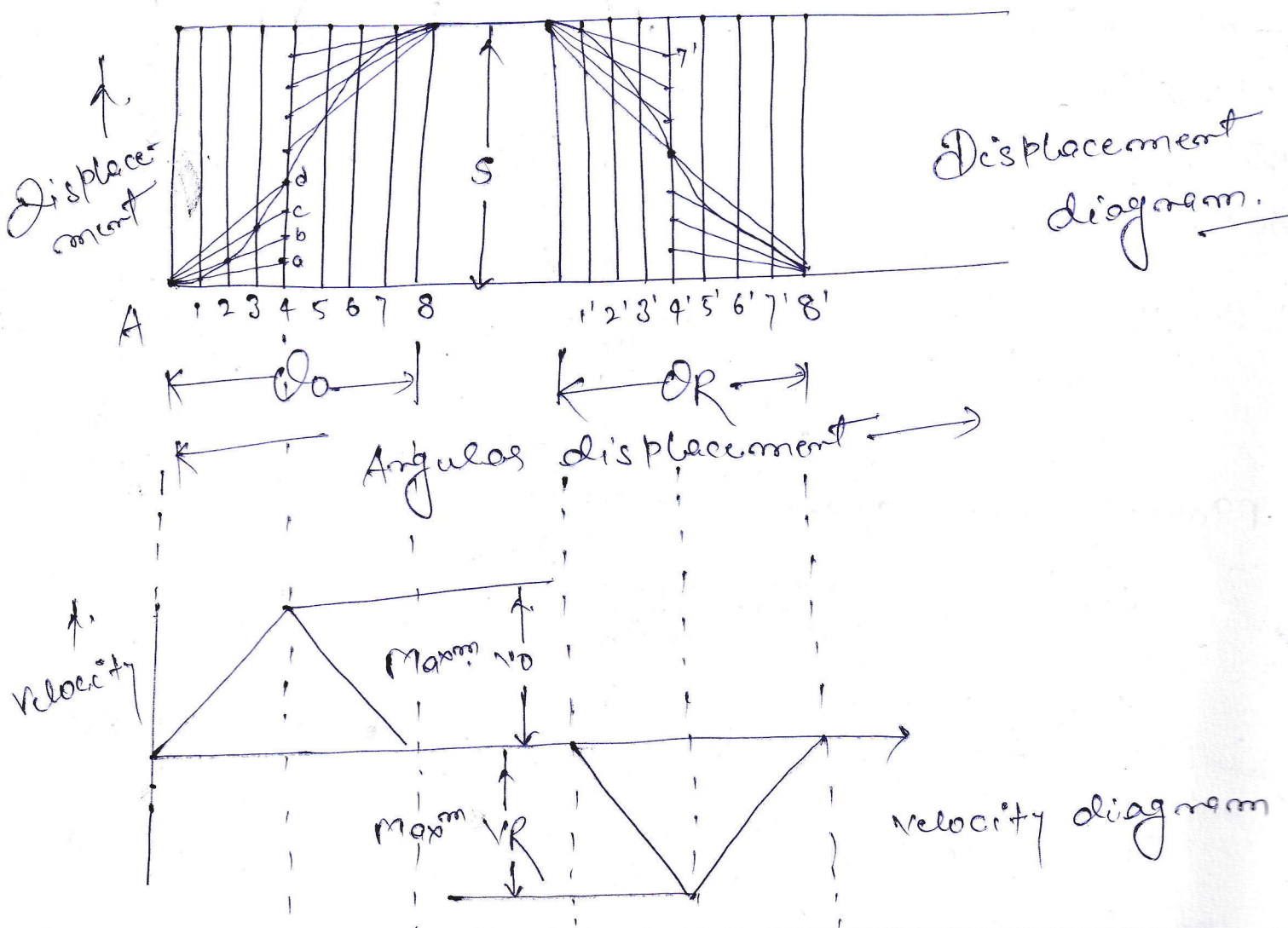
Similarly, Max^m velocity of the follower on the return stroke,

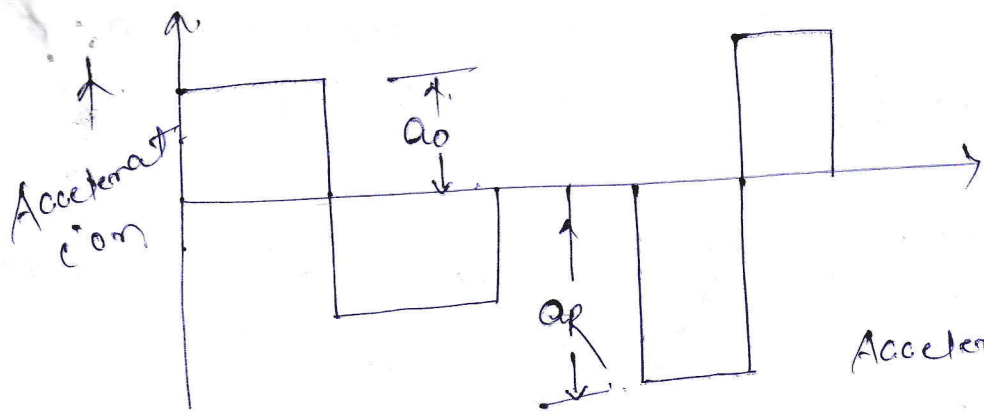
$$V_R = \frac{\pi \cdot \omega \cdot s}{2 \cdot \theta_R}$$

and Max^m Acceleration of the follower on the return stroke,

$$a_R = \frac{\pi^2 \omega^2 s}{2 (\theta_R)^2}$$

(3) Displacement, velocity and Acceleration diagram when the follower moves with uniform acceleration and retardation.





Time required for the follower during out-stroke.

$$t_o = \frac{O_o}{\omega}$$

Similarly for Return stroke

$$t_R = \frac{O_R}{\omega}$$

Mean velocity of the follower during outstroke.

$$= \left(\frac{S}{t_o} \right)$$

Similarly for Return stroke.

$$= \left(\frac{S}{t_R} \right)$$

Maximum velocity of the follower is equal to twice the mean velocity.

Max^m velocity of the follower during outstroke.

$$v_o = 2 \times \left(\frac{S}{t_o} \right) = \frac{2\omega S}{O_o}$$

Similarly for Return stroke.

$$\text{Max^m velocity } v_R = 2 \times \left(\frac{S}{t_R} \right) = \frac{2\omega S}{O_R}$$

The maximum velocity of the follower is reached after the time $(t_o/2)$ during outstroke and $(t_R/2)$ during return stroke.

∴ Maximum acceleration of the follower during outstroke

$$a_o = \frac{v_o}{(t_o/2)} = \frac{2 \times 2 \cdot \omega \cdot s}{t_o \cdot \omega} = \frac{4 \omega^2 s}{(\omega)^2}$$

Similarly max^m acceleration during return stroke

is

$$a_R = \frac{v_R}{(t_R/2)} = \frac{2 \times 2 \cdot \omega^2 \cdot s}{(\omega)^2} = \frac{4 \omega^2 s}{(\omega)^2}$$