

Advance Engineering Mathematics(AEM)

**Branch :Information Technology,
Sem:IIIrd**



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Vision of the Institute

To become a renowned centre of outcome based learning, and work towards academic, professional, cultural and social enrichment of the lives of individuals and communities

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Mission of the Institute

- Focus on evaluation of learning outcomes and motivate students to inculcate research aptitude by project based learning.
- Identify, based on informed perception of Indian, regional and global needs, the areas of focus and provide platform to gain knowledge and solutions.
- Offer opportunities for interaction between academia and industry.
- Develop human potential to its fullest extent so that intellectually capable and imaginatively gifted leaders may emerge.

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Course Outcomes

- **CO2:** To learn the formulation of different mathematical problems into optimization problems.
- **CO3:** Apply the principles of optimization using differential calculus.
- **CO4:** To understand the concepts of Linear Programming
- **CO1:** To learn the concepts and principles of Random variables and Probability distribution.

Linear Programming

- Simplex Method
- Two Phase Method,
- Duality in Linear Programming,
- Assignment Problems,
- Transportation Problems

Simplex Method

- When decision variables are **more than 2**, it is always advisable to use Simplex Method of avoid lengthy graphical procedure.
- The simplex method is not used to examine all the feasible solutions.
- It deals only with a small and unique set of feasible solutions the set of vertex points (i.e. extreme points) of the convex feasible space that contains the optimal solution
- The most popular method used for the solution of Linear programming problems (LPP) is the simplex method. Simplex method is developed by George Dantignin 1946
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When decision variables are *more than 2*, we always use Simplex Method

□ **Slack Variable**: Variable added to a \leq constraint to convert it to an equation (=).

❖ A slack variable represents unused resources .

❖ A slack variable contributes nothing to the objective function value.

□ **Surplus Variable:** Variable subtracted a \geq constraint to convert it to an equation (=).

❖ A surplus variable represents an excess above constraint requirement level.

❖ surplus variables contribute nothing to the calculated value of the objective function.

- ❑ **Basic Solution (BS)** : This solution is obtained by setting any n variables (among $m+n$ variables) equal to zero and solving for remaining m variables, provided the determinant of the coefficients of these variables is non-zero. Such m variables are called **basic variables** and remaining n zero valued variables are called **non basic variables**
- ❑ **Basic Feasible Solution (BFS)** : It is a basic solution which also satisfies the non negativity restrictions.

□ **BFS are of two types :**

- ***Degenerate BFS*** : If once or more basic variables are zero
- ***Non-Degenerate BFS*** : All basic variables are non-zero.

Optimal BFS: BFS which optimizes the objective function

Examples:

$$\text{Max. } Z = 13x_1 + 11x_2$$

Subject to constraints:

$$4x_1 + 5x_2 \leq 1500$$

$$5x_1 + 3x_2 \leq 1575$$

$$x_1 + 2x_2 \leq 420$$

$$x_1, x_2 \geq 0$$

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□ **Step 1:** Convert all the inequality constraints into equalities by the use of slack variables

Let S_1, S_2, S_3 be three slack variables.

Introducing these slack variables into the inequality constraints and rewriting the objective function such that all variables are on the left-hand side of the equation. Model can be rewritten as :

$$Z - 13x_1 - 11x_2 = 0$$

Subject to Constraints:

$$4X_1 + 5X_2 + S_1 = 1500$$

$$5X_1 + 3X_2 + S_2 = 1575$$

$$X_1 + 2X_2 + S_3 = 420$$

$$X_1, X_2, S_1, S_2, S_3 = 0$$

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Reference:

- <https://www.slideshare.net/sachin.mk/simple-x-method>
- Engineering Mathematics III CS/IT Engineering
Vardhan Publication

Thank You

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